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Control signal for PID control without derivative gain limitation: The predicted process output is given by. Combining the above equations for a maximum and minimum control signal (and)which corresponds to the points for which the actuator saturates, If the predicted output is in the proportional band, the controller operates linearly.

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2) between the process liquid and the. coolant. Eqs.1 and 2 comprise the dynamic model for the system. 2. Additional assumptions: i. The density ρ and the specific heat C of the process liquid are. constant. ii. The temperature of steam T_s is uniform over the entire heat. transfer area iii. T_s is a function of P_s , $T_s = f(P_s)$

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